



Dependable positioning for demanding applications

Alain Suskind

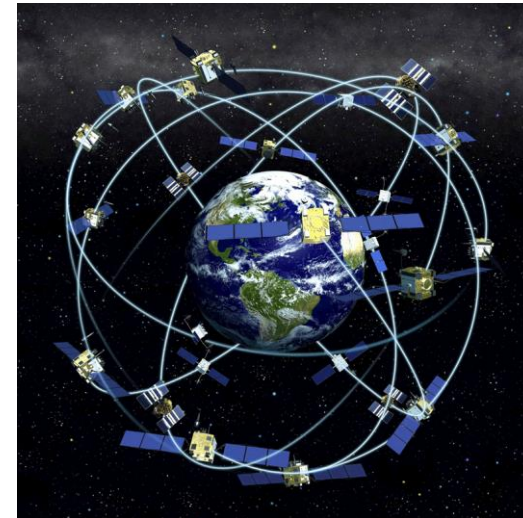
March 8, 2017

Who is Septentrio?

- Your success is our success
 - Most accurate and reliable **GNSS position and timing solutions** in the most demanding industrial environments
- Our team is your team
 - International team of **GNSS HW, SW** and navigation experts developing all core elements of high-quality GNSS receivers.
- Focus on quality
 - Partner with you to provide **high quality products** with excellent integration, application engineering and **service**
- Global Presence
 - Leuven, Belgium with regional branches
 - Los Angeles, CA and Hong Kong.
 - Worldwide partner network



Our roots



Founded Septentrio in 2000.
Major partner & shareholder.
Premier semiconductor research institute.
Unique infrastructure and talent.
Spider in **strong eco-system**.

Long term strategic partner since 2002.
All Galileo test receivers designed and built by Septentrio exclusively (IOV & FOC).
Participated in numerous ESA projects in military, avionics & space.
Provided **in-depth understanding of GNSS**.



Key application markets

Machine Automation

Marine



Construction



Mining



Logistics



Agriculture



Autonomous driving



Survey and Mapping

Survey



GIS



Mobile Mapping



Unmanned Systems



Scientific/Reference

Reference Receivers



Timing Receivers



Space Weather



Aerospace/Defense

Aerospace



Defense



Customers

Machine Automation



Survey and Mapping



Scientific/Reference

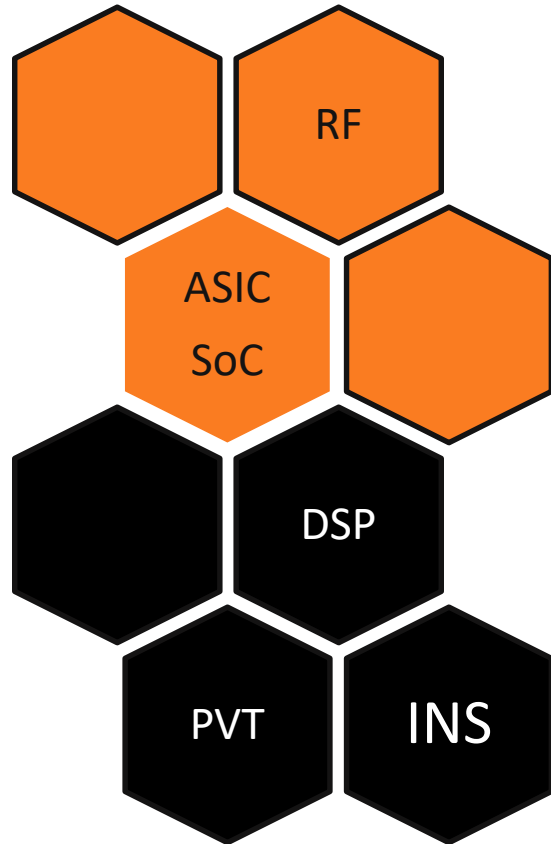


Aerospace/Defense



Technology for Success

We masters all technologies to reliably deliver accuracy in challenging and mission critical environment



- RF front-end and baseband SoC for all **signal-in-space** tracking
- High **interference immunity**
- Advanced **multi-path mitigation**
- Fast acquisition, high sensitivity and low measurement noise
- **Scalable accuracy**: sub-meter down to cm
- High **dependability**
- All GNSS positioning technologies (SBAS, DGNSS, RTK, PPP, SSR)
- GNSS/INS hybridization

Septentrio Positioning and Timing Solutions



Easy-to-integrate



Accuracy



Dependability

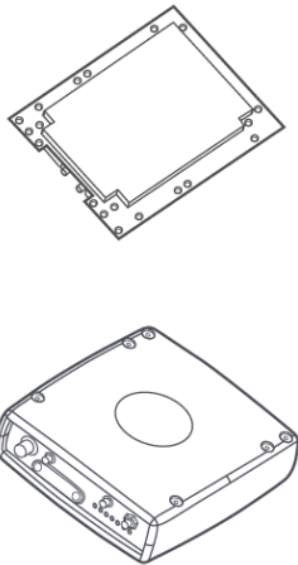


GNSS Technology

Our Professional Products

AsteRx

Rover Receivers and OEM boards
for automation and machine control



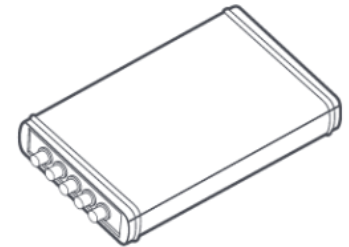
Altus

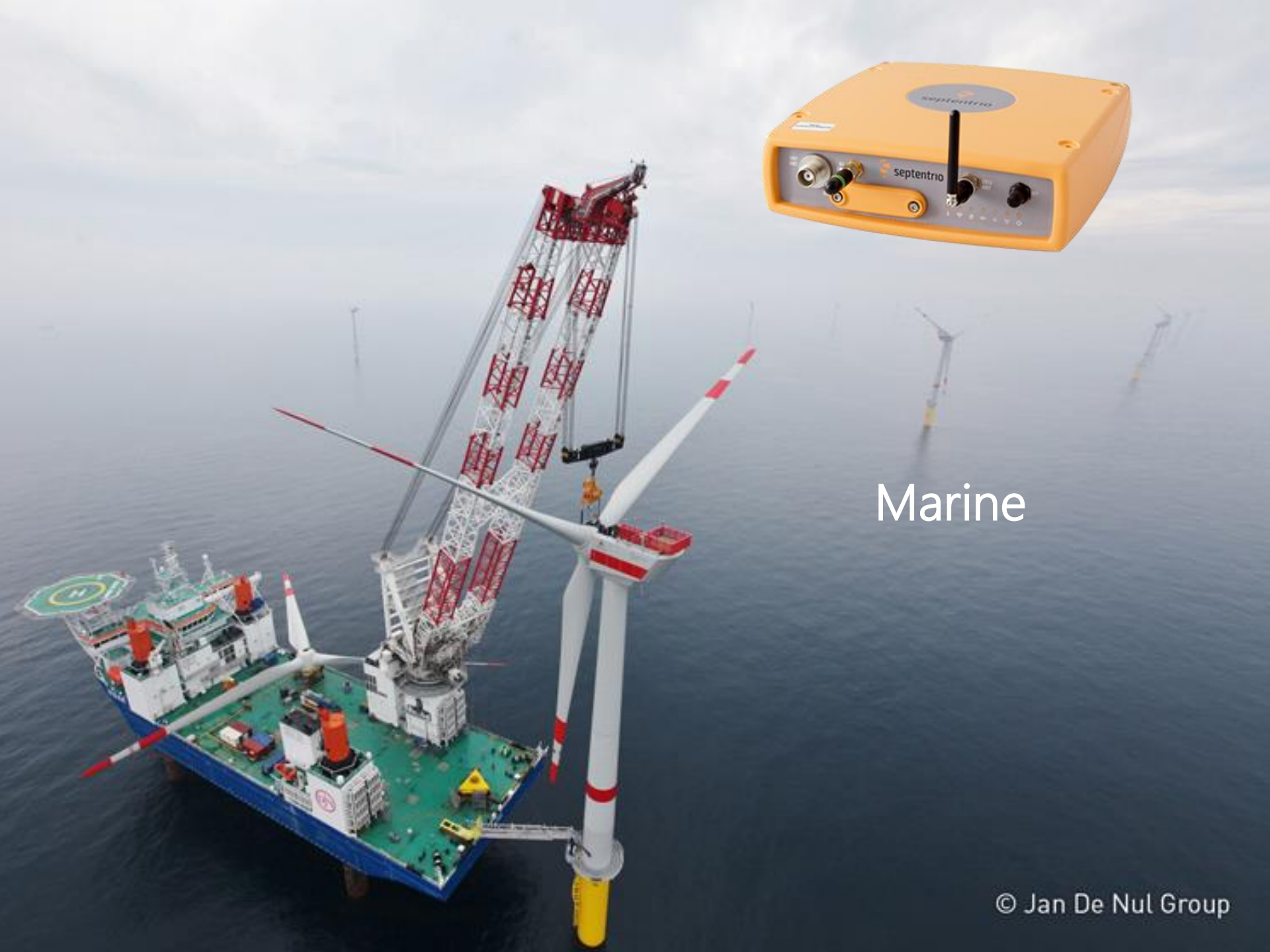
Smart antennas for
GIS and survey



PolaRx

Reference receivers for
science and networks





Marine



Mining & Construction

Machine Control



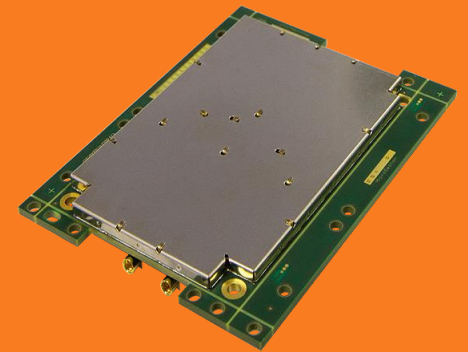


Agriculture

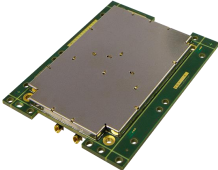
Autosteer

Tool control

Planting Trees



Autosteer and tool control



Planting trees



Dependable positioning in Automotive



Dependable positioning in Automotive

- Before: Road level positioning
 - On which road am I?
 - Use **Autonomous GPS** (accuracy ~5m) + projection on maps
- Now: Lane Level Positioning
 - On which lane am I?
 - Use GNSS + correction (e.g., **EGNOS**, accuracy ~1m) + maps
 - May use **additional sensors**: radar, camera, inertial
- (Close) Future: Autonomous Vehicles
 - Better than lane positioning
 - Dependability (availability, integrity)
 - Requires **Sensor Fusion** and **High Precision GNSS**

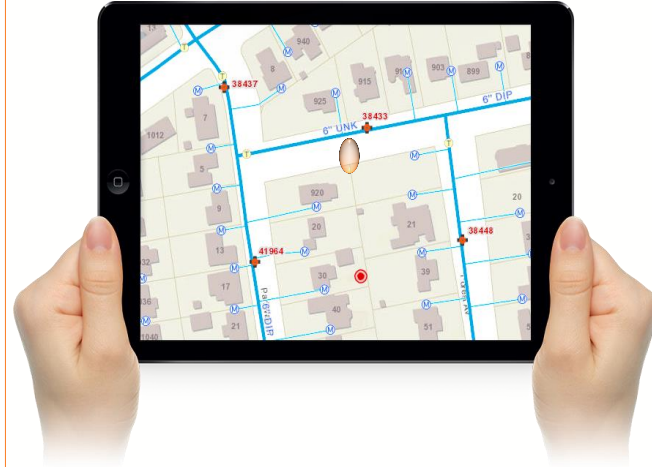
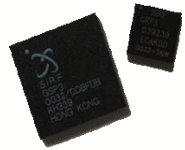


GNSS remains the only viable absolute positioning and timing source

Specific Absolute Positioning Requirements for Autonomous Vehicles

- **Accuracy <1m 3-sigma**
 - 3x better than EGNOS
 - Requires high precision GNSS
 - RTK: local augmentation data from infrastructure (differential)
 - PPP: global augmentation data from Geostationary Satellites (e.g., Inmarsat)
- **Highest possible availability**
 - Requires to use all available systems
 - GPS, GALILEO, GLONASS, BEIDOU, QZSS
 - “Dead reckoning” on other sensors when no satellites systems available (e.g., tunnel)
- **Integrity**
 - Essentially reliability of the error indicator
 - Need sensor fusion
- **Functional Safety**
 - ISO26262
- **Security**
 - Active anti-jamming and anti-spoofing
 - IT security

Survey & GIS: Altus products





Drones

Accurate
Georeferencing

No Ground
Control Points



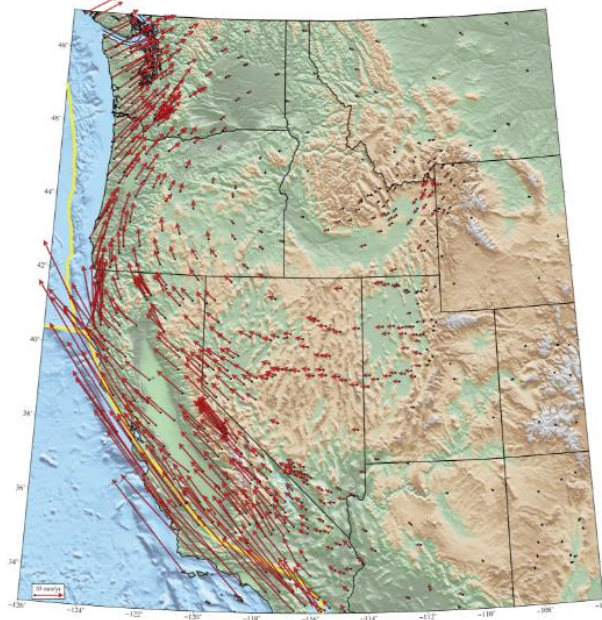
Scientific/Reference

PolaRx5

**Scientific users &
reference stations**



Tectonic Motions of the Western United States

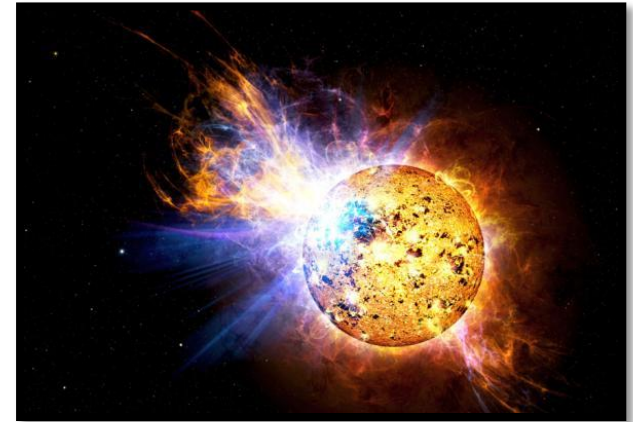


Reference velocities for western United States GPS stations whose data are processed by the Kinship Relativity Extension and EarthScope (KRE) GPS Analysis Center for the Pacific Boundary Observatory at the Nevada Tech and Central Washington University. Velocities are in the North American Reference Frame (NAD83) and are scaled by the International Earth Rotation and Reference Systems Service (IERS). The number of stations shown in California has been greatly reduced to make it easier to see regional motion. For updated velocities, visit the web for IAGGCS GPS Weekly News. See the map credit below for more information.



PolaRx5S

Ionosphere monitoring

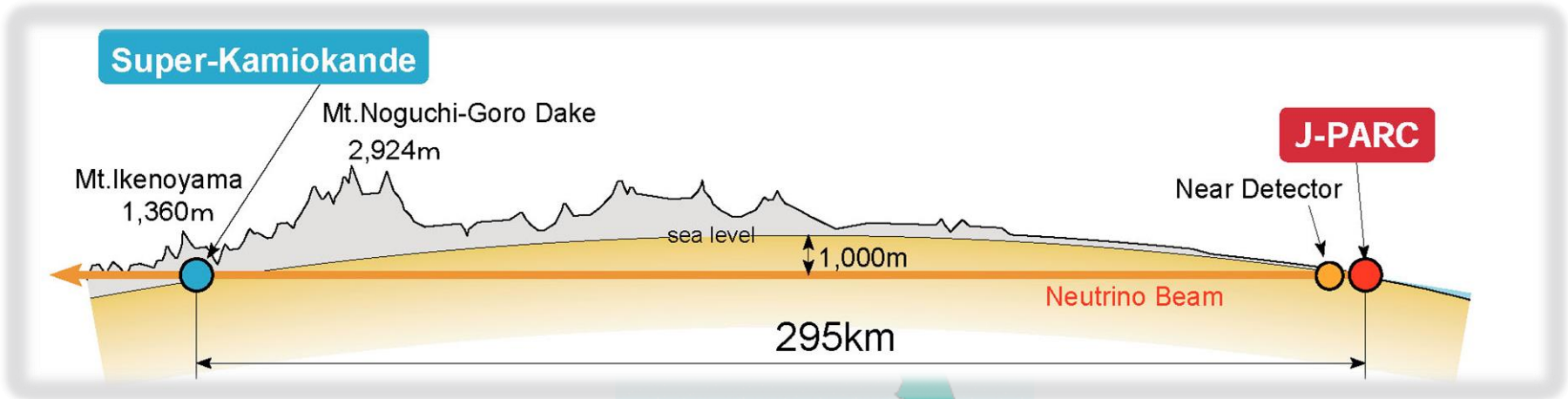
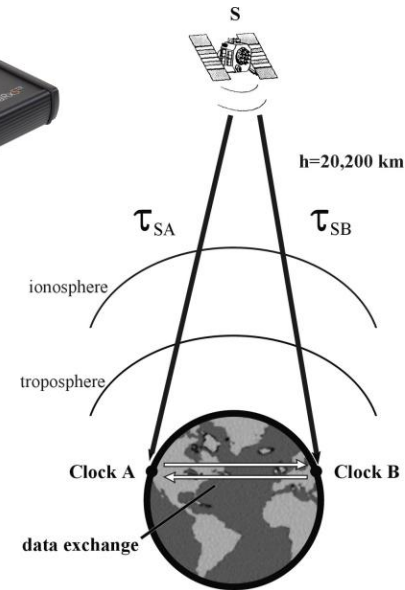


Precise timing application

Long-baseline neutrino experiments

<http://t2k-experiment.org/t2k/>

<http://www.t2k.org/docs/poster/038/NeuTel13-T2KTOFposter>



Interference issues

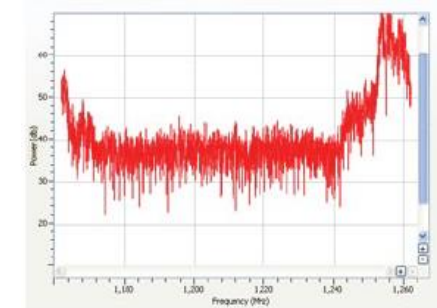
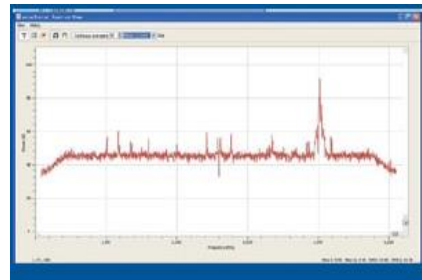
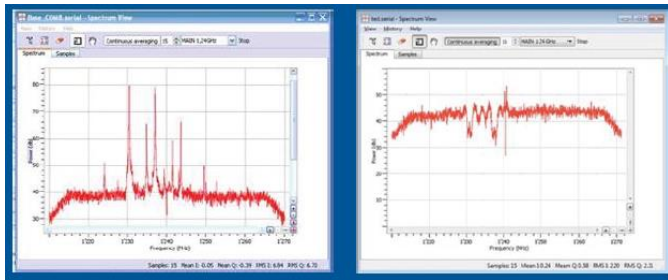
Tuymen Olbast, Russia



Hilversum, the Netherlands



Oostende, Belgium



More satellites ?

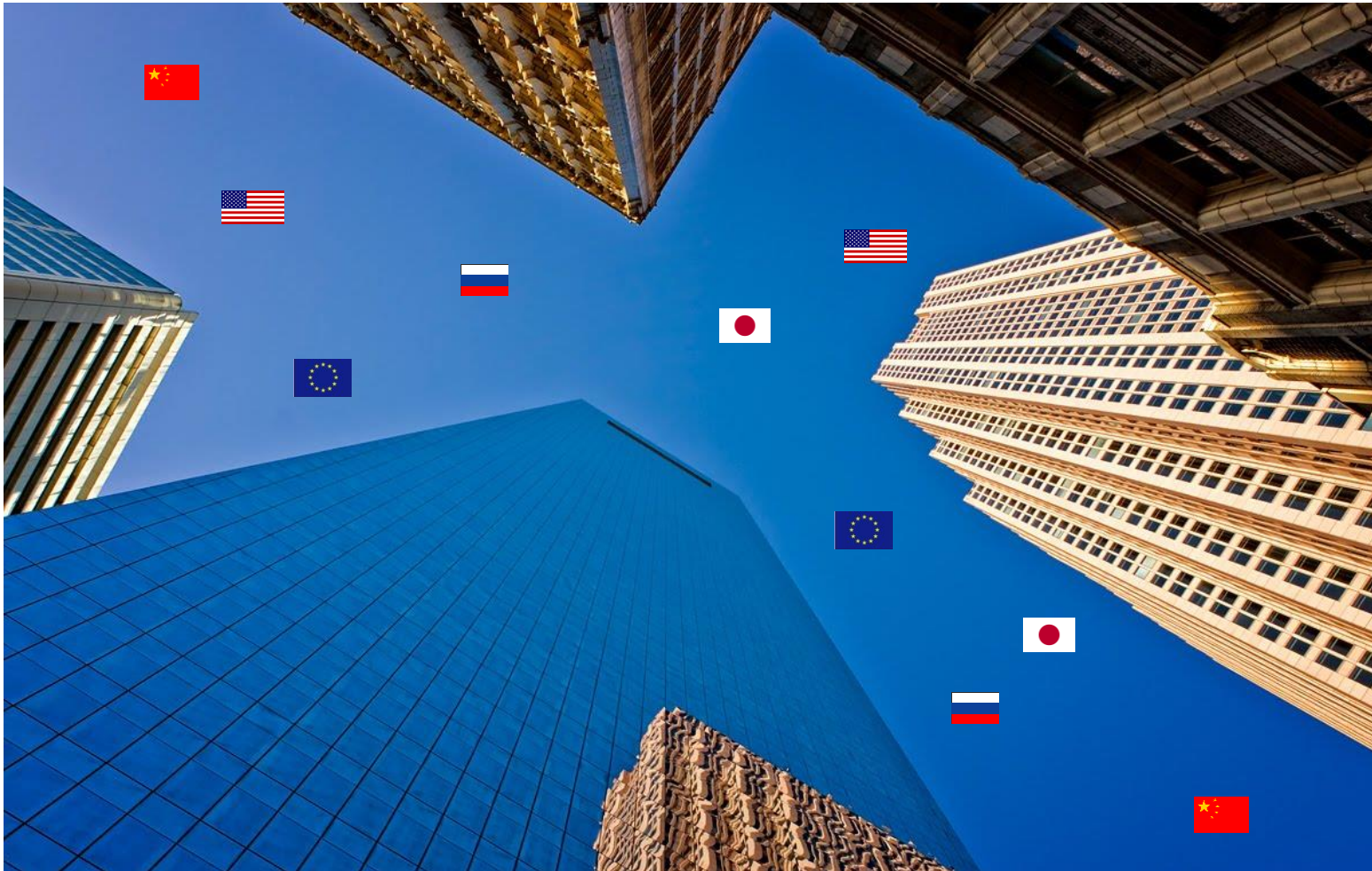
GPS

+ GLONASS

+ GALILEO

+ BEIDOU

+ QZSS





How can we help you ?





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